WEST Search History

DATE: Saturday, April 05, 2003

Set Name side by side	Query	Hit Count	Set Name result set
	DB=USPT,PGPB,JPAB,EPAB,DWPI,TDBD; PLUR=YES; OP=ADJ		
L3	(robot$6 or articulat$3 or automat$6 or autonomous$2 or CNC or machine$2 or mechanical device or mechan$6 or servomechan$4) and handle and zeus or (divinci or di vinci)	59	L3
L2	(robot$6 or articulat$3 or automat$6 or autonomous$2 or CNC or machine$2 or mechanical device or mechan$6 or servomechan$4) and master handle	88	L2
L1	(robot$6 or articulat$3 or automat$6 or autonomous$2 or CNC or machine$2 or mechanical device or mechan$6 or servomechan$4) and master handle and wrist joint and "5 d.o.f. or 5 dof" or five degrees of freedom	0	L1

END OF SEARCH HISTORY

Set Name	Query	Hit Count	Set Name
side by side			result set

DB=USPT,PGPB,JPAB,EPAB,DWPI,TDBD; PLUR=YES; OP=ADJ

Set Name	Query	Hit Count	Set Name
L3	(robot$6 or articulat$3 or automat$6 or autonomous$2 or CNC or machine$2 or mechanical device or mechan$6 or servomechan$4) and handle and zeus or (divinci or di vinci)	59	L3
L2	(robot$6 or articulat$3 or automat$6 or autonomous$2 or CNC or machine$2 or mechanical device or mechan$6 or servomechan$4) and master handle	88	L2
L1	(robot$6 or articulat$3 or automat$6 or autonomous$2 or CNC or machine$2 or mechanical device or mechan$6 or servomechan$4) and master handle and wrist joint and "5 d.o.f. or 5 dof" or five degrees of freedom	0	L1

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